

Lec 19 (Finishing up Alexander's Theorem)

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Theorem 18

i) $f(0) < p_c$ \exists a $C > 0$ st if $|x| \geq C$

ii) $\mathbb{E}[e^{\alpha T_e}] < \infty$ then for sufficiently large n

\exists a lattice path 0 to nx with "a Q_x skeleton" of

at most $m \leq 2n+1$ vertices.

Main ingredient is Kesten's bound: If conditions in

(ii) hold then

$$P(|T(0,x) - \mathbb{E}T(0,x)| \geq u|x|^{1/2}) \leq C_1 e^{-C_2 u}$$

for $u < C_3 |x|$

* Notice that although we have proved Gaussian

concentration with more modern techniques, Alexander

only used Kesten's exponential concentration.

Define $s_x(y) = \mathbb{E}T(0,y) - g_x(y) = h(y) - g_x(y)$

$$\geq g(y) - g_x(y) \geq 0 \quad (\text{by previous})$$

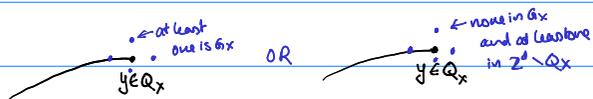
$$s_x(y+z) \leq s_x(y) + s_x(z) \quad (\text{Using subadditivity of } h \text{ and})$$

$$Q_x(1/2, \psi) \quad \psi = \log t$$

$$G_x = \{y \in \mathbb{Z}^d : g_x(y) > g(x)\}$$

$$\Delta_x = \{y \in Q_x : y \text{ is adjacent to } \mathbb{Z}^d \setminus Q_x, y \text{ not adjacent to } G_x\}$$

$$D_x = \{y \in Q_x : y \text{ is adjacent to } G_x\}.$$



We can always assume at least one neighbor will be in $\mathbb{Z}^d \setminus Q_x$ when y is in the Q_x skeleton ($y = \psi_i$) since

ψ_i is always chosen to be maximal (next site is not in Q_x)

Lemma:

1) If $y \in Q_x$ then $g(y) \leq 2g(x)$ and $|y| \leq 2d|x|$

2) If $y \in \Delta_x$ then $g(y) \geq c|x|^{1/2} \log|x|$ ← linear d_i but have not "gone past" $g_x(x)$

3) $y \in D_x$, then $g_x(y) \geq \frac{5g(x)}{6}$ ← linear $d_i \in Q_x$ but have gone past $g_x(x)$

There are reasonable things to believe of course.

1) If $y \in Q_x$ is good, $g_x(y) \leq g(x)$ and even, to

$$g(y) \leq 2g(x) \text{ (Can't be too bad)}$$

$$|y| \leq 2d|x| \text{ (y can't be too far away otherwise } g_x(y) > g(x))$$

2) Basically $\exists a \xrightarrow{y} z \in Q_x$ so $S_x(z) \geq C|x|^{1/2} \log|x|$

(It's bad). No $S_x(y) \geq S_x(z) - S_x(x)$

↳ This can be bounded.

USES Maximality of ν :

3) This is fairly straight forward as well.

$$\begin{array}{c} \vdots \\ \nu_i \\ \vdots \\ \nu_x \end{array} \xrightarrow{z} g_x(z) > g(x) \quad \text{So } g_x(\nu_i) \text{ had to be near} \\ \text{be reasonably big too}$$

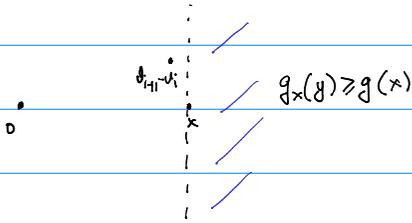
Using this lemma, we can define long and short

increments.

$$S((\nu_i)) = \{i: 0 \leq i < m-1, \nu_{i+1} - \nu_i \in \Delta_x\} \text{ (SHORT)}$$

$$L((\nu_i)) = \{i: 0 \leq i < m-1, \nu_{i+1} - \nu_i \in \mathcal{D}_x\} \text{ (LONG)}$$

The long reason is obvious:



Prop 3.4: If $|x| \geq C$, then for large enough n

\exists a lattice path γ from 0 to x with a Q_x skeleton

of at most $m \leq 2n+1$ vertices.

Idea: There is going to be a lot of points on γ in Q_x
(by BK inequality).

There cannot be too many SHORT increments since
 $S_x(y) > C|x|^{1/2} \log|x|$ and this would violate GAP

There cannot be too many long increments for a
similar reason. This bounds m .

$$P_i^0: \quad Y_i = ET(u_i, u_{i+1}) - T(u_i, u_{i+1})$$

$$0 \leq Y_i \leq ET(u_i, u_{i+1}) \leq E[\tau_e] |u_{i+1} - u_i|$$

$$\Rightarrow P(Y_i \geq u |x|^{1/2}) = 0$$

$$\text{where } u \approx C |u_{i+1} - u_i|$$

But by previous lemma (i) $|u_{i+1} - u_i| \leq 2d|x|$ (#3)

So for $0 \leq u \leq C |u_{i+1} - u_i|$

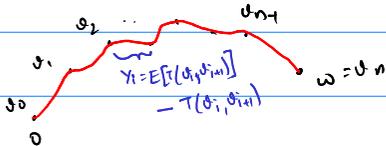
$$P(Y_i \geq u |x|^{1/2}) \leq P(Y_i \geq \frac{u |u_{i+1} - u_i|^{1/2}}{\sqrt{2d}})$$

$$\leq C e^{-cu} \quad \text{(#4) Follows from}$$

the concentration inequality.

$$\Rightarrow E[e^{B_0^2/|x|^{1/2}}] \leq \frac{C}{C - B_0} \quad (\text{exponential bound})$$

Let $T(o, w; (o_j))$ be the minimum passage time among all lattice paths from o to w with Q_x skeleton (o_j) .



It's the minimum over all possible red paths.

Let $\{Y_i\}_{i=1}^n$ be independent copies of the Y_i that are also independent of each other.

By the BK inequality

$$\mathbb{P}\left(\sum_{i=0}^{m-1} Y_i \geq t\right) \leq \mathbb{P}\left(\sum_{i=0}^{m-1} Y_i' \geq t\right)$$

One has to be careful here, and ought to perhaps use Kesten's form of the inequality.

$$\begin{aligned} & \mathbb{P}\left(\bigcup_j A_{m(i,j)} \dots \dots A_{m(i,k(r))}\right) \\ & \leq \sum_j \mathbb{P}(A_{m(i,j)}) \end{aligned}$$

$$\Rightarrow \mathbb{P}\left(\sum_{i=0}^{m-1} \mathbb{E}T(\vartheta_i, \vartheta_{i+1}) - T(D, \vartheta_m) (\vartheta_j) > C_m |x|^{1/2} \log |x|\right)$$

$$\leq \mathbb{P}\left(e^{\beta \sum_{i=0}^{m-1} Y_i' / |x|^{1/2}} > e^{\beta C_m \log |x|}\right)$$

$$\leq e^{-\beta C_m \log |x|} \mathbb{E}\left[e^{\beta \sum_{i=0}^{m-1} Y_i' / |x|^{1/2}}\right] \quad \text{--- (#5)}$$

POLL: Have you have

seen this last inequality?

YES

NO

(#5) becomes

$$\leq \frac{-\beta C_1 m}{e} C_2^m = \frac{-\beta C_1 m}{e} \quad \text{--- (#6)}$$

You can adjust constants so that this is as small as necessary.

We know $|Q_x| \leq 2^d |x|^d$ (by lemma 3.3 (i))

\Rightarrow (#6) says that

The # of Q_x skeletons is $(2^d |x|^d)^m$

Thus $P\left(\sum_{i=0}^{m-1} ET(\vartheta_i, \vartheta_{i+1}) - T(0, \vartheta_m; \vartheta_0) > C m |x|^{1/2} \log |x|\right)$
for some Q_x skeleton

$$\leq (2^d |x|^d)^m e^{-C(\beta)m} \quad \text{(from #6) --- (#7)}$$

The KEY is that we can adjust β and the constants as necessary to make (#7) decay exponentially in m .

Sum (#7) over m to get

$$\begin{aligned} P\left(\sum_{i=0}^{m-1} E T(d_i, d_{i+1}) - T(0, d_m; d_0) > C m |x|^{1/2} \log |x|\right) \\ \text{for some } Q_x \text{ skeleton and for some } m \\ \leq 2e^{-C \log |x|} \quad \text{--- (#8)} \end{aligned}$$

How large can m be? How small can it be?

If you have an m Q_x skeleton

$$\begin{aligned} m g(x) &\geq \sum_{i=0}^{m-1} g_x(d_{i+1} - d_i) = g_x(n x) \\ &\uparrow \qquad \qquad \qquad \uparrow \\ &\text{increments in } Q_x \qquad \qquad \qquad \text{increments in } Q_x \\ &= n g(x) \end{aligned}$$

$$P(T(0, n x) \leq n g(x) + n) \rightarrow 1 \quad \left(\text{since } \frac{T(0, n x)}{n} \xrightarrow[n]{\text{a.e.}} g(x) \right)$$

--- (#8a)

Combining (#8) and (#8a) we choose n

large enough st the intersection of the events in

(#8) and (#8a) have large probability.

$T(D, nx, (0_j)) = T(D, nx) \leq ng(x) + n$

↳ for some Q_x skeleton.

↓

Basically what you have to do is to fix a path γ in the environment and find the sites $(0_i, \dots, 0_m)$ for the particular geodesic γ .

Then by #8

$$\sum_{i=0}^{m-1} \mathbb{E} T(0_i, 0_{i+1}) - T(D, nx, (0_j))$$

$$\leq C_m |x|^{1/2} \log |x|$$

$$\leq ng(x) + n + C_m |x|^{1/2} \log x \leq \underbrace{ng(x) + 2C_m |x|^{1/2} \log |x|}_{(\#9)}$$

using $m \geq n$.

$$\begin{aligned} \sum_{i=0}^{m-1} \mathbb{E} T(0_i, 0_{i+1}) &= \sum_{i=0}^{m-1} (g_x(0_{i+1} - 0_i) + s_x(0_{i+1} - 0_i)) \\ &\geq g_x(nx) + |S(0_i)| C_1 |x|^{1/2} \log |x| \end{aligned}$$

\uparrow linearity \uparrow # of shaded increments

Combining with (#9) we get

$$g_x(nx) + |S(0_i)| C_1 |x|^{1/2} \log |x| \leq ng(x) + 2C_m |x|^{1/2} \log |x|$$

I think
$$g_x(nx) = g\left(\left(nx \cdot \frac{x}{|x|}\right) \frac{x}{|x|}\right)$$

$$= g(nx)$$

⇒ The # short increments is bounded.

$$|s(v_i)| \leq \frac{C_2 m}{c_1} \leq \frac{m}{h}$$

Again, you need to be careful with the constants here!

Next to bound long increments

$$ng(x) + 2Cm\sqrt{|x|} \log|x| \geq \sum_{i=0}^{m-1} \mathbb{E}T(v_i, v_{i+1})$$

$$= \sum_{i=0}^{m-1} (g_x(v_{i+1} - v_i) + \underbrace{s_x(v_{i+1} - v_i)}_{\geq 0})$$

$$\geq |L(v_i)| \frac{5g(x)}{6} \quad \text{using the definition of long increments.}$$

$$|L(v_i)| \leq \frac{6n}{5} + \frac{2Cm\sqrt{|x|} \log(x)}{g(x)} \frac{6}{5}$$

Then we $g(x) \geq C|x|$ since it's a norm.

$$\leq \frac{6n}{5} + \frac{m}{8} \quad (\text{by choosing } |x| \text{ large but finite})$$

So

$$m = |S(v_i)| + |L(v_i)| \leq \frac{6n}{5} + \frac{m}{8} + \frac{m}{4}$$

$$\Rightarrow \frac{m}{8} \leq \frac{6n}{5} \Rightarrow m \leq 2n$$

There is an interplay in the last part going from the random v_i to the deterministic that I haven't completely digested. But this will have to do, in the interest of time.

